DCmind Brushless Datasheet

80 370 001 - V1*

Direct motor

Series

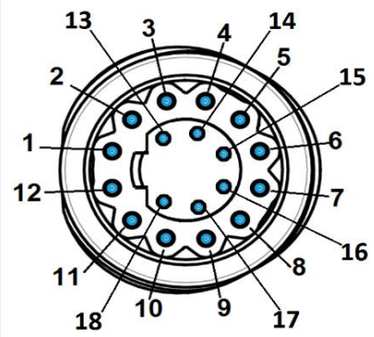
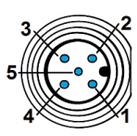
80 370 SMI22 CAN

General characteristics

Power supply		
Direct current voltage supply		✓
Nominal voltage range	Vdc	9 -> 75
Max. current	A	**75**

Motor characteristics (1)		32 Vdc	48 Vdc	60 Vdc	
At no load					
Max. output speed	rpm	2 300	3 420	4 320	
Current at the max output speed	A	1	1	1	
Standby current	mA	50	50	50	+-10%
At nominal					
Speed	rpm	2 000	3 130	3 890	+-10%
Torque (2)	N.m	1,9	1,9	1,9	
Output power	W	398	623	700	+-10%
Current	A	15,1	15,1	15,1	
Efficiency	%	80	86	78	
At max. output power					
Speed	rpm	1 650	2 340	3 170	
Torque	N.m	5	6	6	
Output power	W	864	1 470	1 800	
Current	A	40	44	44	
Efficiency	%	67	70	68	
At peak torque					
Speed	rpm	1 650	2 340	3 170	
Torque	N.m	5	6	6	
Output power	W	864	1 470	1 800	
Current	A	44	44	44	

Others		
Life	h	20 000
Rotor inertia	gcm²	763
Rotor poles		8
Cogging torque	mNm	75
Weight	kg	3,3
Noise level	dBA	55

Connecting		
I/O M16 connector 18 pins	**Pin N°**	
Optional logic supply	1	
0 Volt	2	
Input 6 (analogic 1)	3	
Input 5 (analogic 2)	4	
Input 1 (digital)	5	
Input 2 (digital)	6	
Input 3 (digital)	7	
Input 4 (digital)	8	
0 Volt	9	
Output 1 (digital - PWM)	10	
Output 2 (digital - PWM)	11	
Output 3 (digital)	12	
Output 4 (digital)	13	
0 Volt	14	
STO 2 -	15	
STO 2 +	16	
STO 1 -	17	
STO 1 +	18	
Power supply M16 connector 3 pins	**Pin N°**	
Output ballast	1	
+VDC	2	
0 Volt	3	
CAN M12 Connector - 5 pins	**Pin N°**	
Not connected	1 / 2	
CAN_GND	3	
CAN_H	4	
CAN_L	5	

Drive		
Type	**SMI22 CAN**	
Built-in drive	✓	
Internal magnetic encoder	4096 pulses/rev	
Setting software on PC	DCmind soft+CANopen	
Control		
Position - speed - torque	✓	
4 quadrants	✓	
With regenerative energy absorber (3)	✓	
Type" Field Oriented Control"	✓	
Security		
Wrong polarity from power supply	✓	
Output shortcut	✓	
Input inverted	✓	
Low voltage	0	< 9
Overvoltage (4)	0	> 75
Internal drive temperature protection	°C	110
Temperature drive allowing to restart	°C	90

Generic parameters				
Output shaft with ball bearings			✓	
2 Safe Torque Off inputs		IEC61800-5-2/62061, ISO13849	✓	
Max. radial force	(16mm from front face)		N	140
Max. axial force			N	47
Temperature range		IEC60068-2-1/2	°C	-30 -> +70
Storage temperature			°C	-40 -> +80
Dielectric	(1s/2mA)	UL1004-1	Vdc	1 955
Motor insulation		IEC60085	class	E
Salt spray		ISO9227	severity	48h
Degree of protection (output shaft not included)		IEC60529		IP67 + IP69
EMC				
Electrostatic discharge		IEC61000-4-2	level	3
Radiated field		IEC61000-4-3	level	3
Electrical fast transient/burst test		IEC61000-4-4	level	3
Surge test		IEC61000-4-5	level	1
Conducted disturbances		IEC61000-4-6	level	3
Radiated emission		EN55022	class	B
Approvals				
ROHS		2011/65/CE	✓	
EC			✓	
UL			Pending	
CAN Open		CIA 301 - DSP 402	✓	
Communication				
USB (Setting, monitoring)			Micro-USB B	
CAN open: address - node ID (factory settings)				0x20
CAN open: baud rate (factory settings)			kbaud	1000

Notes
Values without tolerances are average production values.
(1) Cold motor, 20°C ambient temp., full speed, sinusoidal commutation
(2) Nominal torque for continuous operation at 20 °C, decrease this value for higher ambient temperature
(3) Ballast resistor to be added
(4) Can be configured via DCmind soft+CANopen
* V1: see label on product

Additionnal information is available in the SQ75 product user manual and in the starter kit manual, available in www.crouzet.com

Specifications subject to change without notice. Updated 03.10.2019

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Drive electrical data

Running data				
Parameters		Min.	Typical	Max.
Voltage power supply "Vdc"	Vdc	9	24	75
Current "Idc"	A	-	15	60
Standby power "Wo"	W	-	2	-
Voltage optional logic supply (see wiring diagram)	Vdc	9	-	75*

** UL: maximum voltage supply: 36 Vdc*

CAN Bus characteristics				
Parameters		Min.	Typical	Max.
CAN_L	insulated	0,5	1,5	2,25
CAN_H	insulated	2,75	3,5	4,5

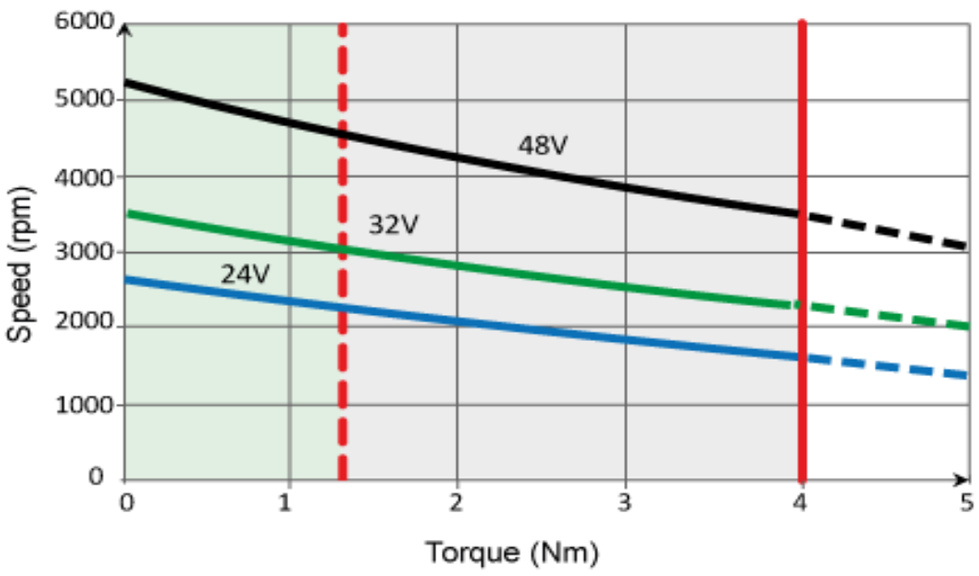
Input data					
Parameters			Min.	Typical	Max.
Input 1, 2, 3, 4	Impedance	kΩ	-	247	-
	Low level	Vdc	-90	-	2,4
	High level	Vdc	4,5	-	90
Input 5, 6	Impedance	kΩ	-	159	-
	Low level	Vdc	-90	-	2
	High level	Vdc	7,1	-	90
Inputs STO	Low level	Vdc	-2	-	4
	High level	Vdc	4,6	-	75

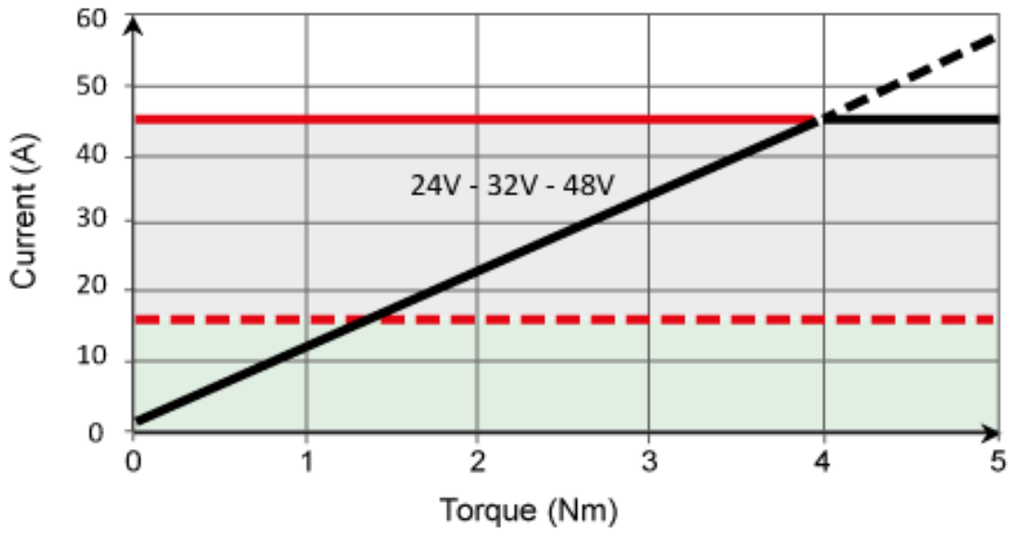
Output data				
Parameters		Min.	Typical	Max.
Low level Output 1, 2, 3, 4	mVdc	-	-	10
High level Output 1, 2, 3, 4	Vdc	-	4,75	-
Max output current "I outmax"	mA	-	-	50
I sink	mA			600

Accessories

Starter kit			
Part number **79 513 105** Power/logic/CAN 3 m cables - Software - USB to Can Open adapter - CAN terminal resistor - CAN double connector			
Power supply cable	79 298 664	3m length	AWG18
Input-Output cable	79 513 106	3m length	AWG24
CAN cable M12	27 358 015	1m length	AWG26

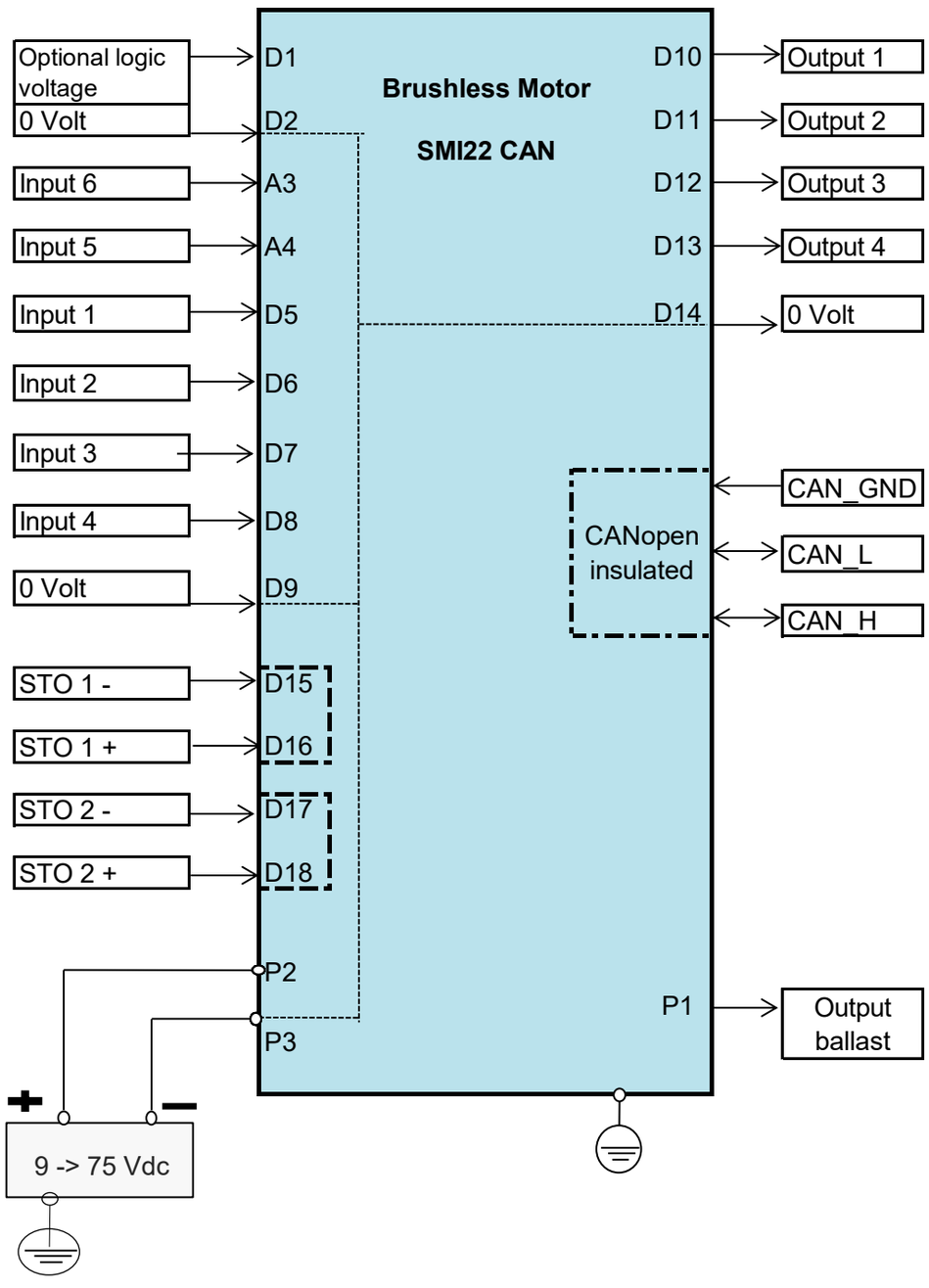
Speed-torque and current-torque curves





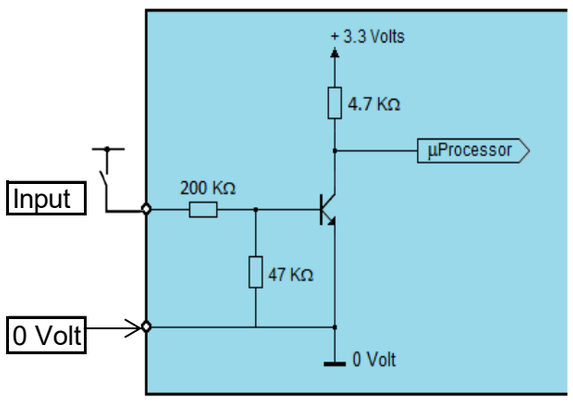
Nominal — Peak — Continuous running — Cycling

Wiring

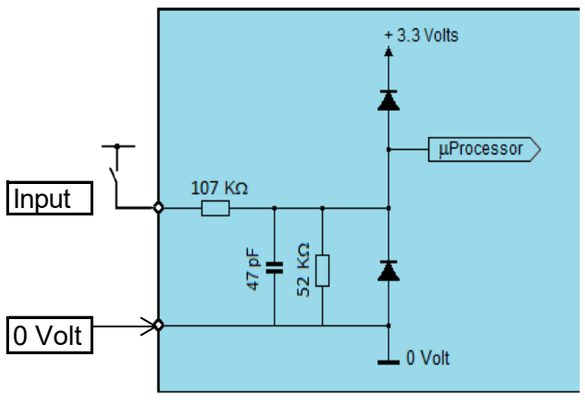


Input equivalent circuit

Inputs 1, 2, 3, 4

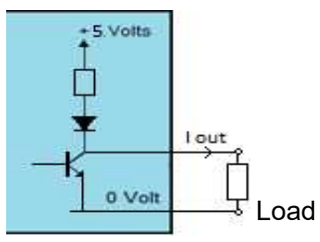


Inputs 5, 6

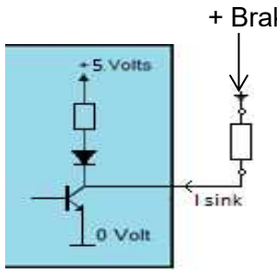


Output equivalent circuit

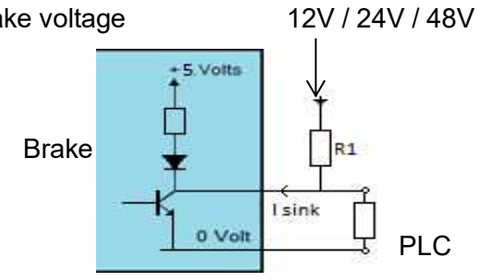
Output 1,2,3,4



I out max = 50 mA

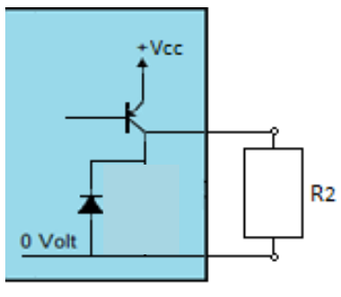


I sink max = 600 mA



I sink max = 600 mA
ex R1 = 10 Kohms - 1/2W
R1 = 2 Kohms - 2W

Output ballast



Regenerative energy created per inertia load creates over-voltage. In case of too high value, connect R2 resistor through ballast output and ground to absorb this energy. Typical R2 value is 2.2 Ω. Power value depends from machine inertia. Max. voltage can be set.

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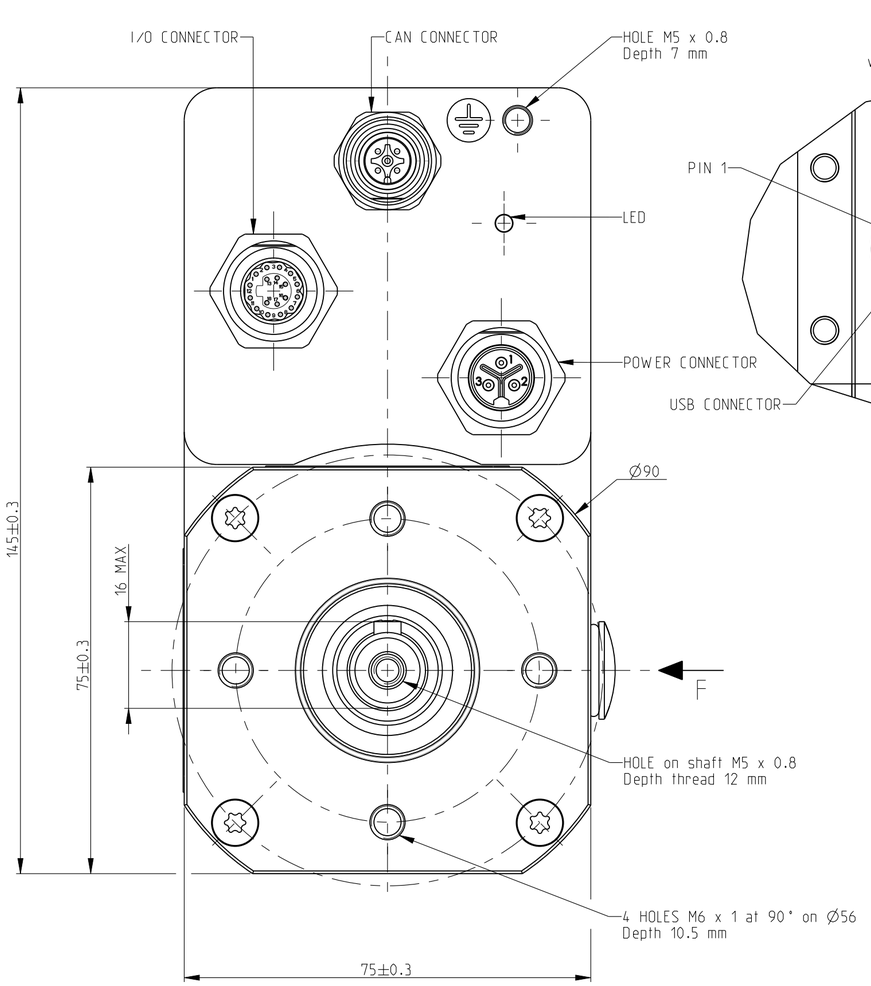

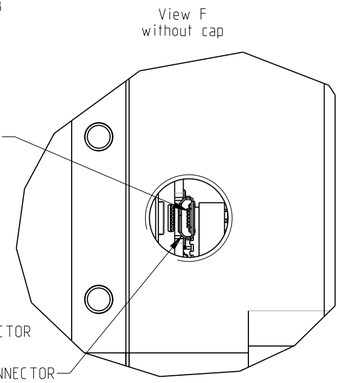

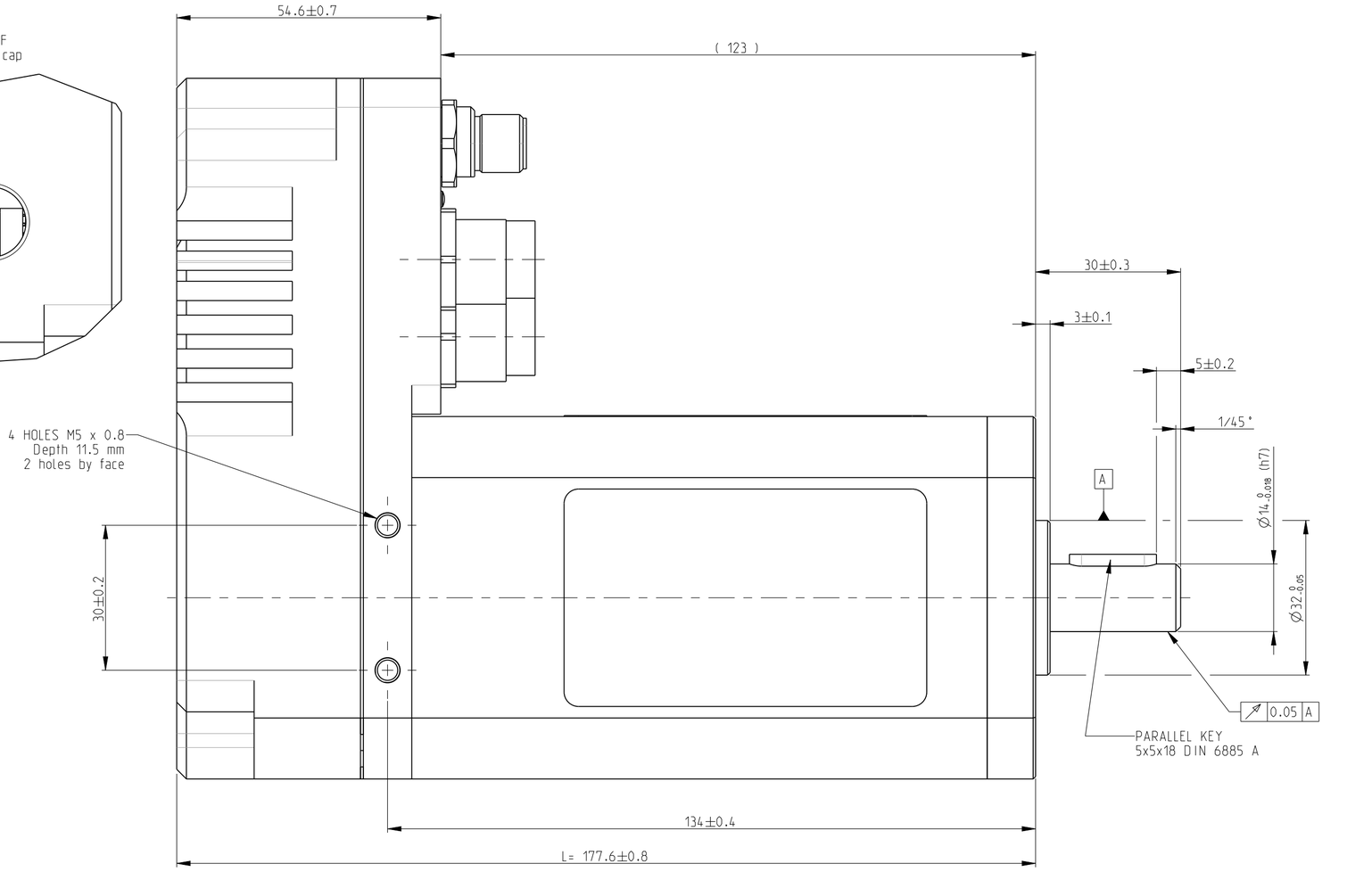

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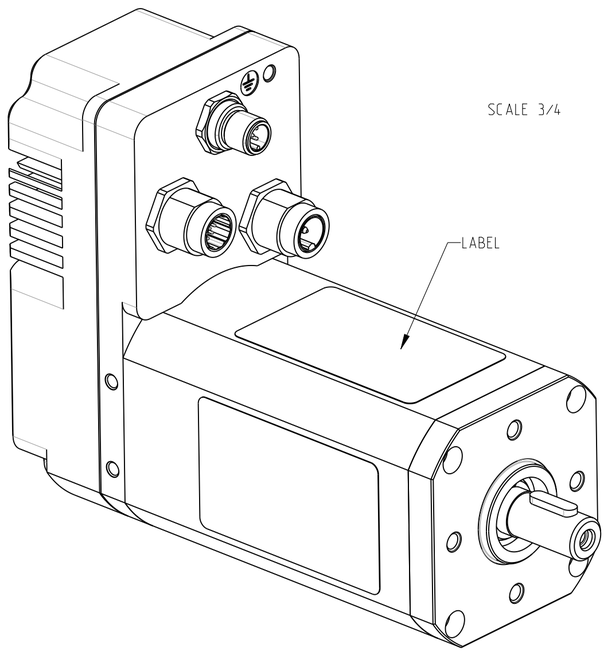

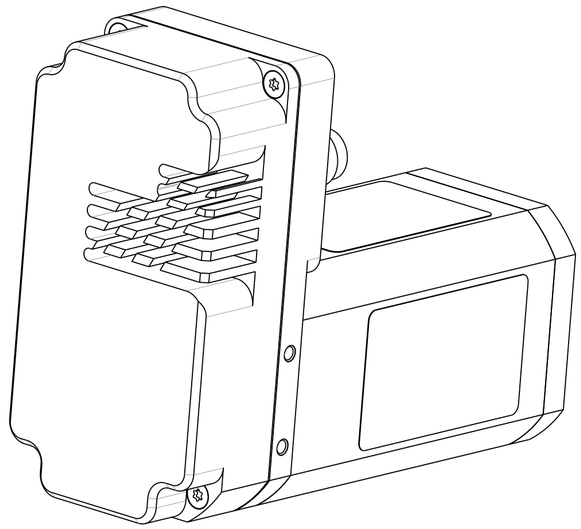

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